# Fire Fighting with Pick and Place Robot.

**Tanpure Rohit Balkrushna [*1], Pagare Kunal Pravin[*2], Varpe Onkar Navnath [*3], Salve Anand Dattu[*4], Prof. Shubham Kailas Sonawane[*5]**

[*1](Department of Electrical Engineering, M. S. B. T. E., Sanjivani K .B. P. Polytechnic, Kopargaon, Maharashtra, India Email: rtanpure97@gmail.com)

[*2](Department of Electrical Engineering, M. S. B. T. E., Sanjivani K .B. P. Polytechnic, Kopargaon, Maharashtra, India Email: kunalpagare054@gmail.com)

[*3](Department of Electrical Engineering, M. S. B. T. E., Sanjivani K .B. P. Polytechnic, Kopargaon, Maharashtra, India Email: onkarvarpe99@gmail.com)

[*4](Department of Electrical Engineering, M. S. B. T. E., Sanjivani K .B. P. Polytechnic, Kopargaon, Maharashtra, India Email: anandsalve78752@gmail.com)

[*5](Department of Electrical Engineering, M. S. B. T. E., Sanjivani K .B. P. Polytechnic, Kopargaoan, Maharashtra, India Email: sksonawaneee@sanjivani.org.in)

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## Abstract:

This Project presents the design and development of a Fire Fighting Robot integrated with a Pick and Place mechanism. The main objective of this system is to detect and extinguish fire automatically while also handling small objects in hazardous environments. The robot is equipped with flame sensors to detect fire sources and a water pump or fire extinguishing mechanism to control the fire.Additionally, the robot includes a robotic arm with a pick and place feature that can remove small obstacles, carry essential materials, or place fire extinguishing components in critical areas. The system is controlled using a microcontroller such as Arduino, enabling autonomous or remote operation.This` project aims to enhance safety by reducing human involvement in dangerous fire accidents, especially in industries, laboratories, and warehouses. The integration of fire detection and object handling makes the system more efficient, reliable, and suitable for emergency response applications.

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## I. INTRODUCTION

Industrial robots contributing a lot to this process of automation in the industry. One of the complex and diverse applications of industrial robots is the anthropometric robotic arm, which resembles the human arm with respect to degrees of freedom and functions and is primarily designed to enable automation with a human a tou touch. The robotic arm ar operates on a controlled motion of DC geared ared motor motor with a remote controlled. This thesis focuses on the analysis and simulation of the control system of the DC geared motors. The motor parameters are modeled and simulated ulated with the use of RF frequency. The control system of the

DC geared motor is then analyzed and designed based on the simulation results with the use of root locus technique. Design of the controller parameters is cast into a conventional optimization problem in this paper. The primary goal of the controller is to ensure that the control system behaves in a stable manner. Different types of controllers are developed for the DC motor control system. The disturbance analysis of the controllers developed is also carried out to come to the conclusion which controller is best suited for the DC motors used in the robotic arm.

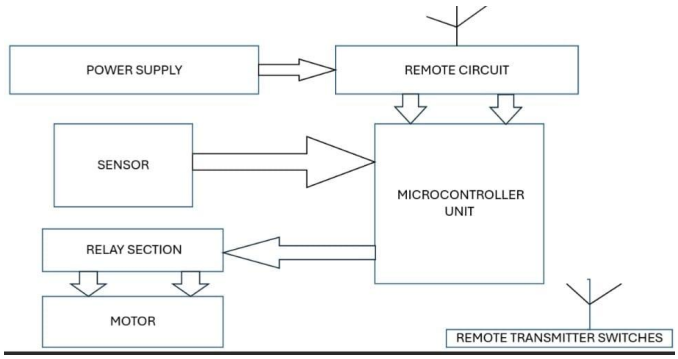
## II. LITERATURE SURVEY

In research paper [1], P. Saravanan and Soni Ishawarya: These researchers are noted for their work researchers work on an "Android controlled integrated semi-autonomous firefighting robot". This system combines mobility for navigation, sensors for fire detection, and a microcontroller for control, with the "integrated" concept potentially including a manipulator for interacting with objects.

In research paper [2], Kristi sti Kosasih, , E. E. Merry Sartika, and M. Jimmy Hasugian: Published a paper in 2010 titled "The Intelligent Fire Fighting Tank Robot." Their work involves an intelligent tank-style robot, which could be relevant to manipulator and pick- and-place functionality in fire emergencies.

In research paper [3], T.N. Khoon, P. Sebastian, and A.B.S. Saman: In their 2012 paper, "Autonomous Fire Fighting Mobile Platform," they discuss a mobile fire-fighting robot that uses a fan to extinguish flames. While it doesn't explicitly mention "pick and place," it does address the autonomous navigation and fire suppression systems that such a robot would need.

## III. BLOCK DIAGRAM




## IV. FUTURE SCOPE & INCREMENTATIONS

- Al-Based Fire Detection

In the future, the robot can be integrated with Artificial Intelligence and image processing to detect fire and smoke more accurately using cameras

- loT Integration

The system can be connected to the Internet of Things (loT) to send real-time alerts and live location updates to fire stations or emergency services.

- Automatic Water Refilling System

An automatic water refilling mechanism can be added to increase working time during large fire accidents.

- Gas and Temperature Sensors

Advanced sensors can be installed to detect harmful gases and high temperature levels for better safety analysis.

- Autonomous Navigation (GPS & Mapping)

Future versions can use GPS and mapping technology for fully autonomous movement in large industries or buildings.

- Heavy-Duty Robotic Arm

The pick and place mechanism can be upgraded to handle heavier objects and debris during rescue operations.

- Voice or Mobile App Control

The robot can be controlled using a smartphone application or voice commands for easier operation.

## V. SUMMARY

The Fire Fighting Robot with Pick and Place mechanism is designed to detect and extinguish fire while handling small objects in dangerous

environments. The robot uses flame sensors to identify fire and activates a water pump or extinguishing system to control it. A microcontroller controls the entire system, allowing either autonomous or remote operation.

In addition to fire detection, the robot is equipped with a robotic arm that can pick up and place objects. This feature helps in removing small obstacles, carrying safety materials, or placing fire extinguishing tools in risky areas. The integration of both firefighting and object handling functions makes the system more efficient and useful in emergency situations.

This project reduces human risk during fire accidents and improves safety in industries, laboratories, offices, and warehouses. It demonstrates how robotics and automation can be used effectively in disaster management and rescue operations.

## VI. CONCLUSION

The Fire Fighting with Pick and Place Robot project demonstrates an innovative and practical solution for handling fire-related emergencies while reducing human risk. This system is designed to detect fire, extinguish it automatically, and safely pick and place hazardous or important objects away from the affected area.

By integrating fire sensors, a microcontroller-based control system, water pump mechanism, and robotic arm technology, the robot ensures quick response and efficient fire suppression. The pick-and-place mechanism adds additional functionality by allowing the robot to remove flammable materials or rescue small objects from dangerous zones.

This project highlights the importance of automation and robotics in safety applications. It reduces dependency on human intervention in high-risk environments such as industries, warehouses, and laboratories. Overall, the Fire Fighting Pick and Place Robot improves safety, enhances efficiency, and represents a significant step toward smart emergency response systems.

## VII. REFERENCES


- P. Saravanan and Soni Ishawarya: These researchers are noted for their work on an “Android controlled integrated semi-autonomous firefighting robot”. This system combines mobility for navigation, sensors for fire detection, and a microcontroller for control, with the “integrated” concept potentially including a manipulator for interacting with objects.
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